

4-8 设 $K = \begin{pmatrix} k_{11} & k_{12} & \dots & k_{15} \\ k_{21} & \dots & & k_{25} \\ k_{31} & \dots & & k_{35} \end{pmatrix}$ $A+BK = \begin{pmatrix} 0 & 1 & 0 & 2 & 1 \\ 0 & 0 & 1 & 4 & 3 \\ 7+k_{31} & 6+k_{32} & 4+k_{33} & 3+k_{34} & 1+k_{35} \\ 8+2k_{21} & 7+2k_{22} & 5+2k_{23} & 9+2k_{24} & 3+2k_{25} \\ 5-k_{11} & 8-k_{12} & 6-k_{13} & 2-k_{14} & 9-k_{15} \end{pmatrix}$

令 $8+2k_{21} = 7+2k_{22} = 5+2k_{23} = 0$

$5-k_{11} = 8-k_{12} = 6-k_{13} = 0$

~~$9+2k_{24} = 0$~~ , ~~$9-k_{15} = 0$~~

$3+k_{34} = 1+k_{35} = 0$, $3+2k_{25} = 2-k_{14} = 0$

$9+2k_{24} = -2$, $9-k_{15} = -3$,

则 $A+BK = \begin{pmatrix} 0 & 1 & 0 & 2 & 1 \\ 0 & 0 & 1 & 4 & 3 \\ 7+k_{31} & 6+k_{32} & 4+k_{33} & 0 & 0 \\ 0 & 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & 0 & -3 \end{pmatrix} = \begin{pmatrix} A_{11} & A_{12} \\ 0 & A_{22} \end{pmatrix}$

对左上角块配置即可. $|\lambda I - A_{11}| = \lambda^3 - (k_{33}+4)\lambda^2 - (k_{32}+6)\lambda - (k_{31}+7)$

期望多项式为 $(\lambda+4)(\lambda+1+j)(\lambda+1-j) = \lambda^3 + 6\lambda^2 + 10\lambda + 8$

$\therefore k_{33} = -10$, $k_{32} = -16$, $k_{31} = -15$

综上. $K = \begin{pmatrix} 5 & 8 & 6 & 2 & 12 \\ -4 & -3.5 & -2.5 & -5.5 & -1.5 \\ -15 & -16 & -10 & -3 & -1 \end{pmatrix}$

4-9 斜坡输入. 因此需要两个积分器.

$$\begin{cases} \dot{z}_1 = e = y - y_r \\ \dot{z}_2 = z_1 \end{cases}$$

系统方程为: $(A) \begin{pmatrix} \dot{x} \\ \dot{z}_1 \\ \dot{z}_2 \end{pmatrix} = \begin{pmatrix} A & 0 & 0 \\ C & 0 & 0 \\ 0 & I & 0 \end{pmatrix} \begin{pmatrix} x \\ z_1 \\ z_2 \end{pmatrix} + \begin{pmatrix} B \\ 0 \\ 0 \end{pmatrix} u + \begin{pmatrix} d \\ -y_r \\ 0 \end{pmatrix}$ $y = Cx = [c \ 0 \ 0] \begin{pmatrix} x \\ z_1 \\ z_2 \end{pmatrix}$

状态反馈为: $u = [k_1 \ k_2 \ k_3] \begin{pmatrix} x \\ z_1 \\ z_2 \end{pmatrix} = k_1 x + k_2 z_1 + k_3 z_2$

闭环系统方程为:

$$(B.) \quad \begin{cases} \dot{x} \\ \dot{z}_1 \\ \dot{z}_2 \end{cases} = \begin{pmatrix} A+Bk_1 & Bk_2 & Bk_3 \\ C & 0 & 0 \\ 0 & I & 0 \end{pmatrix} \begin{pmatrix} x \\ z_1 \\ z_2 \end{pmatrix} + \begin{pmatrix} d \\ -y_r \\ 0 \end{pmatrix}$$

$$y = [C \ 0 \ 0] \begin{pmatrix} x \\ z_1 \\ z_2 \end{pmatrix}$$

定理 4-7. (A.) 可控的必要条件是 4-18 可控. ~~rank~~ $\begin{bmatrix} A & B \\ C & 0 \end{bmatrix} = n+r$

且 $\text{rank} \begin{pmatrix} A & 0 & B \\ C & 0 & 0 \\ 0 & I & 0 \end{pmatrix} = n+z_1+z_2 = n+2q$

定理 4-8. 设 k_1, k_2, k_3 使得 (B.) 的特征值均有负实部. 干扰与输入均为斜坡.

即 $d(t) = \bar{d} \cdot t$, $y_r(t) = \bar{y}_r \cdot t$, 则 $\dot{x}(t), \dot{z}_1(t), \dot{z}_2(t)$ 均趋于常量, $y(t)$ 趋于 $y_r(t)$

证明: 对 (B.) Laplace 变换.

$$\begin{pmatrix} X(s) \\ Z_1(s) \\ Z_2(s) \end{pmatrix} = \begin{pmatrix} sI - (A+Bk_1) & -Bk_2 & -Bk_3 \\ -C & sI & 0 \\ 0 & -I & sI \end{pmatrix}^{-1} \begin{pmatrix} d(s) \\ -y_r(s) \\ 0 \end{pmatrix}$$

$$d(s) = \bar{d} \cdot \frac{1}{s^2}, \quad y_r(s) = \bar{y}_r \cdot \frac{1}{s^2}$$

由终值定理,

$$\lim_{t \rightarrow \infty} \begin{pmatrix} \dot{x}(t) \\ \dot{z}_1(t) \\ \dot{z}_2(t) \end{pmatrix} = \lim_{s \rightarrow 0} s \cdot \begin{pmatrix} sX(s) \\ sZ_1(s) \\ sZ_2(s) \end{pmatrix} = \begin{pmatrix} -(A+Bk_1) & -Bk_2 & -Bk_3 \\ -C & 0 & 0 \\ 0 & -I & 0 \end{pmatrix}^{-1} \begin{pmatrix} \bar{d} \\ -\bar{y}_r \\ 0 \end{pmatrix}$$

而 $\lim_{t \rightarrow \infty} \dot{z}_2(t) = \text{常量}$, 即 $\lim_{t \rightarrow \infty} e^{st} = 0$.

4-11

$$C_1 B = [0 \ 0] \quad \cancel{C_1 A B} = [28 \ -13] \quad \text{故 } d_1 = 1 \quad E_1 = [28 \ -13]$$

$$C_2 B = [0 \ 0] \quad C_2 A B = [2 \ 5] \quad \text{故 } d_2 = 1 \quad E_2 = [2 \ 5]$$

$E = \begin{bmatrix} 28 & -13 \\ 2 & 5 \end{bmatrix}$ $|E| \neq 0$ 故可以用 $u = kx + Hv$ 将闭环化为积分器解耦系统

$$F_1 = C_1 A^2 = \begin{bmatrix} -5 & 0 & 9 & -7 \\ \underline{\underline{-4}} & \underline{\underline{-2}} & \underline{\underline{1}} & \underline{\underline{-2}} \end{bmatrix} \quad F_2 = C_2 A^2 = [-2 \ -4 \ 1 \ -2]$$

$$F = \begin{bmatrix} -5 & 0 & 9 & -7 \\ -2 & -4 & 1 & -2 \end{bmatrix}$$

$$\therefore H = E^{-1} = \begin{pmatrix} \frac{5}{166} & \frac{13}{166} \\ \frac{-2}{166} & \frac{28}{166} \end{pmatrix} \quad K = -E^{-1}F = \begin{pmatrix} \frac{51}{166} & \frac{52}{166} & \frac{-58}{166} & \frac{61}{166} \\ \frac{46}{166} & \frac{112}{166} & \frac{-10}{166} & \frac{42}{166} \end{pmatrix}$$

$$A+BK = \begin{pmatrix} \frac{14}{83} & \frac{-2}{83} & \frac{15}{83} & \frac{20}{83} \\ \frac{28}{83} & \frac{-4}{83} & \frac{30}{83} & \frac{40}{83} \\ \frac{-60}{83} & \frac{56}{83} & \frac{78}{83} & \frac{104}{83} \\ \frac{58}{83} & \frac{-44}{83} & \frac{-66}{83} & \frac{-88}{83} \end{pmatrix} \quad BH = \begin{pmatrix} \frac{2}{83} & \frac{-42}{83} \\ \frac{6}{83} & \frac{-1}{83} \\ \frac{-1}{83} & \frac{14}{83} \\ \frac{20}{83} & \frac{-31}{83} \end{pmatrix}$$

$$G_f(s) = \begin{bmatrix} \frac{1}{s^2} \\ \frac{1}{s^2} \end{bmatrix} \quad \Delta G_f(s) = 4 = d_1 + d_2 + p \quad \therefore \text{解耦与稳定不矛盾}$$

4-13

a. $C_1 B = [1 \ 0] \quad \cancel{C_1 A} = d_1 = 0, \quad E_1 = [1 \ 0]$
 $C_2 B = [0 \ 0] \quad C_2 A B = [1 \ 1] \quad d_2 = 1, \quad E_2 = [1 \ 1]$

$\therefore E = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \quad |E| \neq 0, \text{ 可以动态解耦}$

$F_1 = C_1 A = [-1 \ 0 \ 0] \quad F_2 = C_2 A^2 = [-4 \ 4 \ 5]$

$\therefore F = \begin{bmatrix} -1 & 0 & 0 \\ -4 & 4 & 5 \end{bmatrix}$

$\therefore H = E^{-1} F = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 0 & 1 \end{bmatrix} \quad K = -E^{-1} F = \begin{bmatrix} 1 & 0 & 0 \\ 3 & -4 & -5 \end{bmatrix} \quad u = kx + Hv$

b. PBH 不难判断, 系统可控.

且 $\det \begin{bmatrix} A & B \\ C & 0 \end{bmatrix} \neq 0$, 故可以静态解耦

设 $K = \begin{bmatrix} k_{11} & k_{12} & k_{13} \\ k_{21} & k_{22} & k_{23} \end{bmatrix} \quad A+BK = \begin{bmatrix} k_{11}-1 & k_{12} & k_{13} \\ k_{21} & k_{22}-2 & k_{23}-4 \\ 1-k_{21} & -k_{22} & 1-k_{23} \end{bmatrix}$ 令 $k_{11}-1 = -1, k_{22}-2 = -2, 1-k_{23} = -3, k_{12} = 0$
~~其余=0~~, 则 $A+BK = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -2 & 0 \\ 1 & 0 & -3 \end{bmatrix}$
 $k_{13} = 0, k_{21} = 0$

$\therefore K = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 4 \end{bmatrix}$

$H = -[C(A+BK)^{-1}B]^{-1}M, \quad \text{取 } M = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad \text{则 } H = \begin{bmatrix} 1 & 0 \\ -2 & 6 \end{bmatrix}$

4-15

$G_1 B = [1 \ 0]$ $G_2 B = [0 \ 1]$ $E = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ 非奇异 故可以动态解耦.

$$[\lambda I - A \ B] = \begin{bmatrix} \lambda & 0 & 0 & 1 & 0 \\ 0 & \lambda & -1 & 0 & 0 \\ 1 & 2 & \lambda+3 & 0 & 1 \end{bmatrix} \text{行满秩, 故系统可控.}$$

$$\begin{bmatrix} A & B \\ C & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ -1 & -2 & -3 & 0 & 1 \\ 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix} \leftarrow \begin{array}{l} \text{第2,5行相关, } \det \begin{bmatrix} A & B \\ C & 0 \end{bmatrix} = 0, \text{ 故不能静态解耦.} \\ \leftarrow \end{array}$$

4-17 $G_1 B = [1 \ 0]$ $G_2 B = [0 \ 0]$ $G_2 A B = [1 \ 1]$ $\therefore d_1=0 \ d_2=1$

$$E = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \quad \delta G_f(s) = 3 = d_1 + d_2 + p \quad \therefore \text{可以}$$

$$\therefore H = E^{-1} = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \quad F_1 = G_1(A+3I) = [2 \ 0 \ 0] \quad F_2 = G_2(A^2+3A+2I) = [-1 \ 0 \ -2]$$

$$\therefore F = \begin{bmatrix} 2 & 0 & 0 \\ -1 & 0 & -2 \end{bmatrix} \quad K = -E^{-1}F = \begin{bmatrix} -2 & 0 & 0 \\ 3 & 0 & 2 \end{bmatrix}$$